

# **Time Series Analysis: Models and Methods (A Survey\*)**

\*Some figures and sections are adopted from tutorial by E. Fox in ICML'15

**The Data Science and Decisions Lab, UCLA**

March 2016

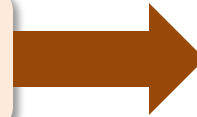
# General Procedure for time series modelling: when, how and why?

Validation, **statistical efficiency**

**Problem**



**Model**



**Evaluation**

- 1- Forecasting
- 2- Hypothesis testing
- 3- Control
- 4- Clustering
- 5- Learning structure & dynamics

Pick a model based on the structure of the problem and the validity of assumptions

# Medical Problems involving Time Series Analysis

## 1- Forecasting: -> **Regression analysis**

Predicting future values of physiological measurements, predicting length of a hospital's waiting list, predicting population level spread of epidemics, survival analysis, etc.

## 2- Hypothesis testing: -> **Early classification**

Detecting disorders, confounding effects of treatments, testing patients' latent classes, etc.

## 3- Control: -> **Planning interventions over time**

## 4- Clustering:-> **Learning similarities across temporal data**

## 5- Learning structure & dynamics:-> **Learning causalities**

# Medical References involving Time Series Analysis

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... and many more...

# How to start?

## Intuition and understanding the idiosyncrasies of the problem!

Is the series stationary? Disorders?

Strong **mixing**?

Multiple dependent series?

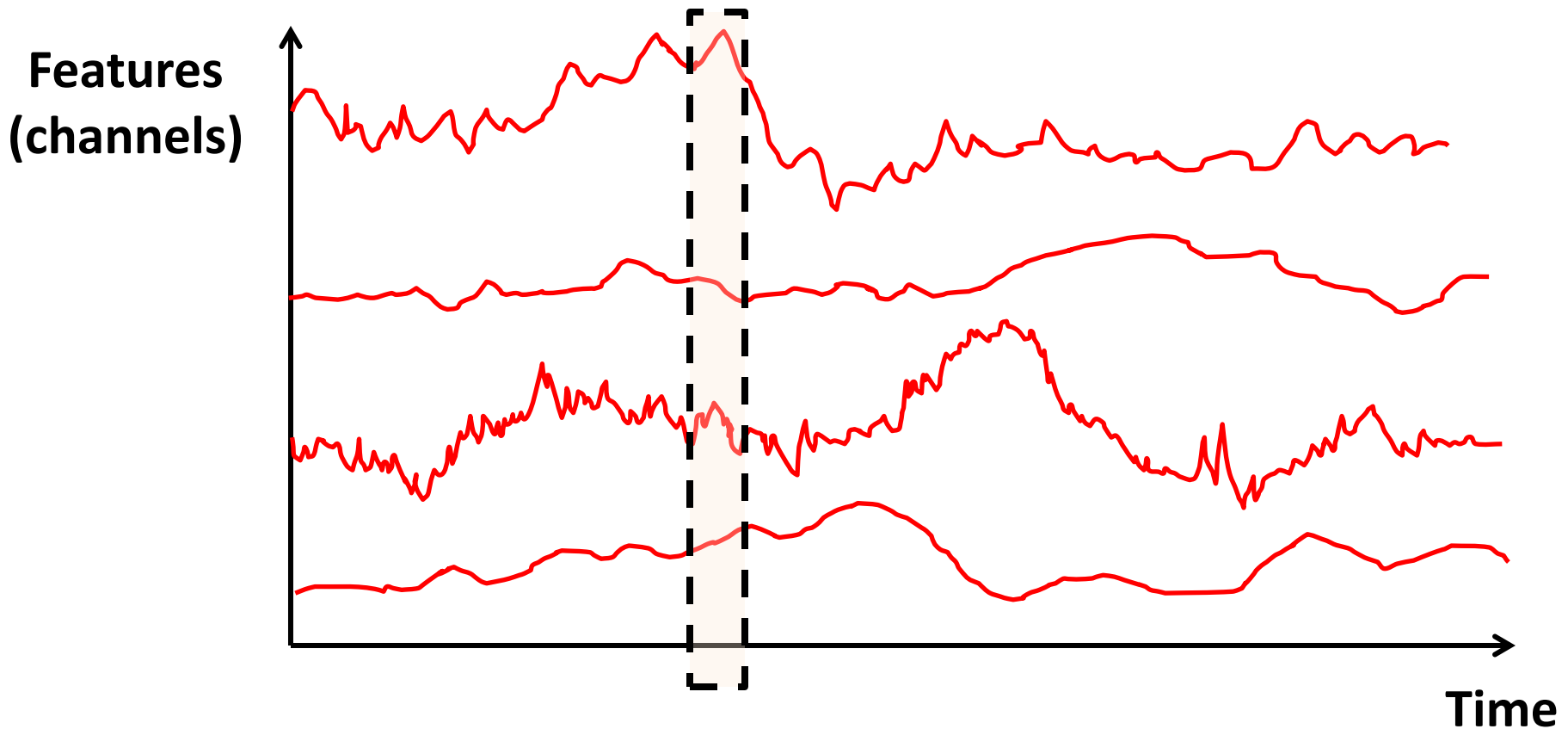
Causalities between series?

Exogenous interventions?

Pick a set of  
Models

Evaluate and  
eliminate

# The two dimensions of multivariate time series



Every model captures:

**Evolution:** impacts timeliness of decisions and accuracy of predictions

**Relational structure:** impacts cost, computational and statistical efficiency

# 1) Autoregressive Moving Average Models (ARMA)

## Assumptions

Underlying process being modeled is (weakly) stationary: the process exhibits no trends over time (i.e. constant mean and variance).

## Construction: univariate ARMA(p,q) model

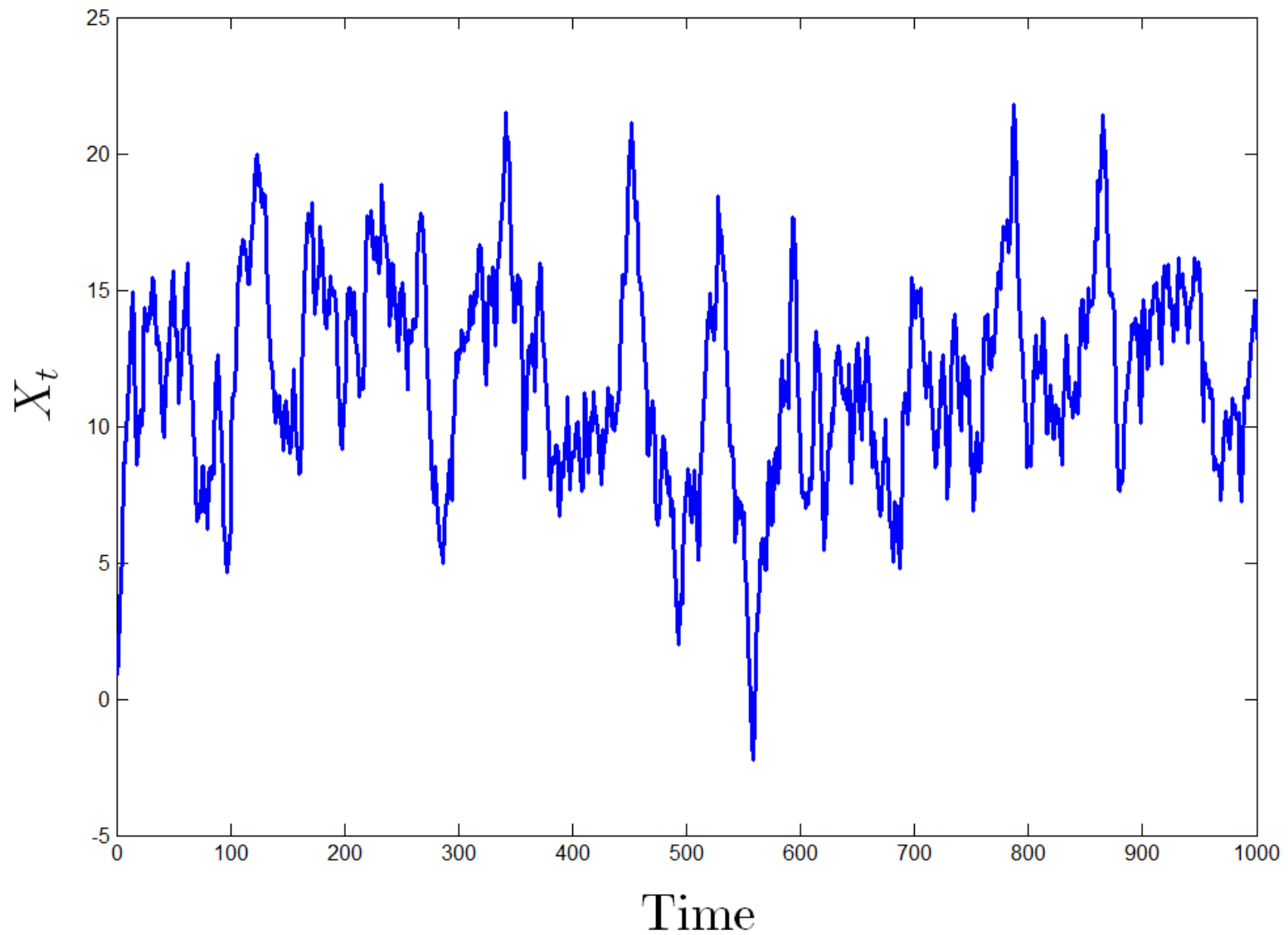
$$X_t = c + \epsilon_t + \sum_{i=1}^p \alpha_i X_{t-i} + \sum_{i=1}^q \beta_i \epsilon_{t-i}$$

Diagram illustrating the components of the univariate ARMA(p,q) model equation:

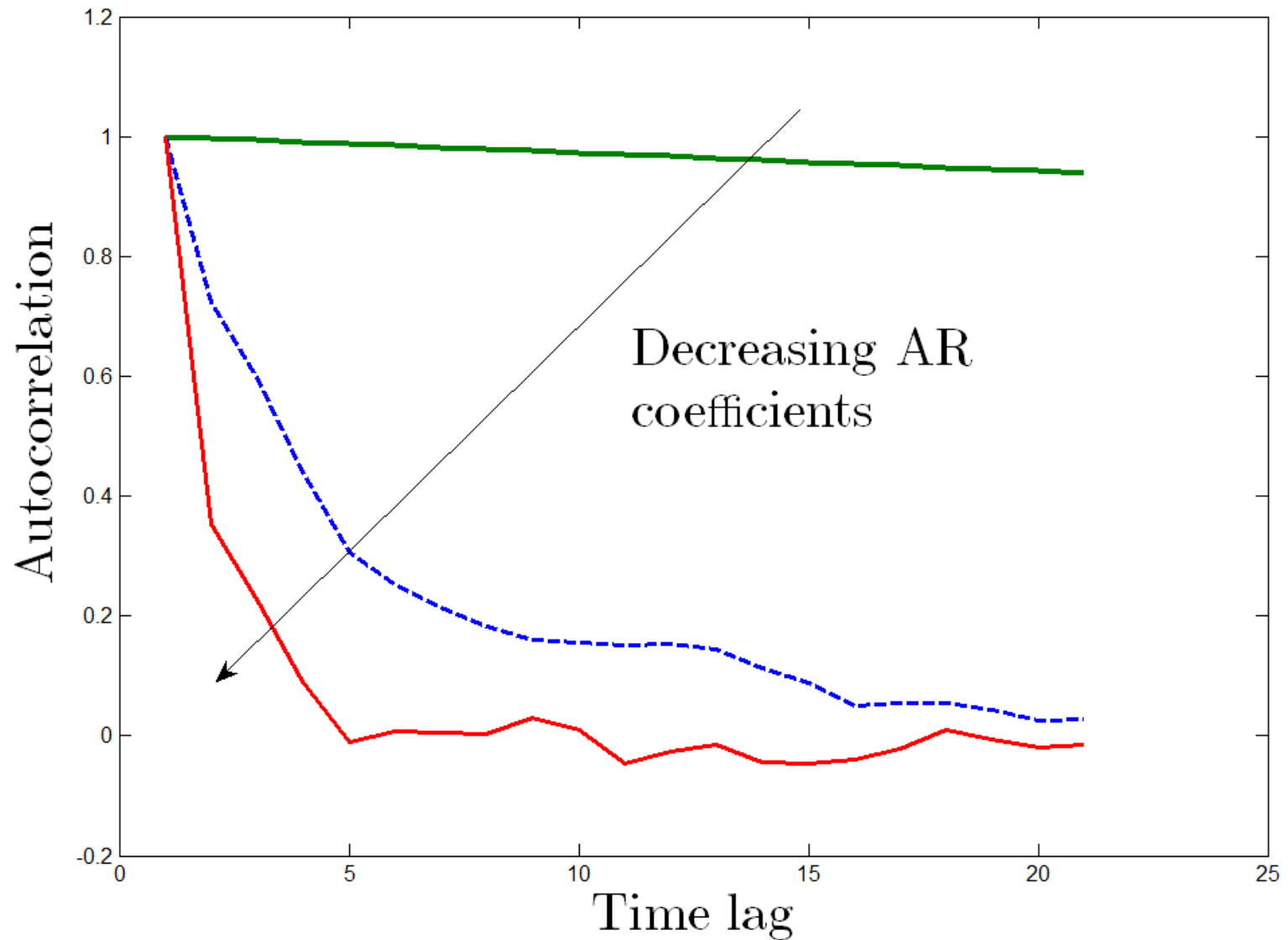
- $c$ : Constant
- $\epsilon_t$ : Gaussian noise
- $\alpha_i$ : AR coefficients
- $\beta_i$ : MA coefficients



# 1) ARMA: stationarity of the generative model



# 1) ARMA model capturing evolution



# 1) Multivariate ARMA model

Evolution described by AR and MA coefficients, what about relational structure?

**Construction: multivariate ARMA(p,q) model**

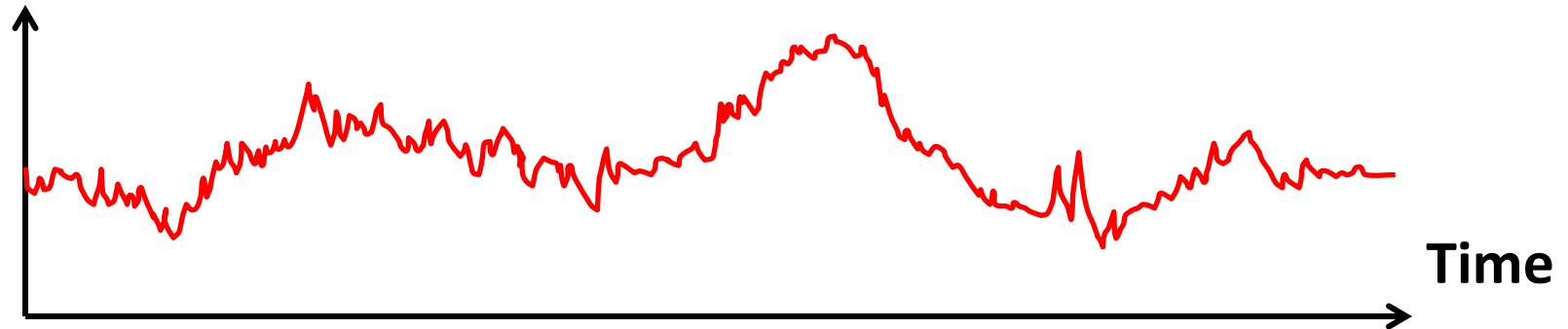
$$\mathbf{X}_t = c + \epsilon_t + \sum_{i=1}^p \mathbf{A}_i \mathbf{X}_{t-i} + \sum_{i=1}^q \mathbf{B}_i \epsilon_{t-i}$$

Companion matrix (AR matrix) and MA matrix  
capture the relational structure

**Variant constructions can capture drifts, periodicity, etc. E.g. ARIMA and seasonal ARIMA.**

# 1) Fitting the ARMA model

Learning the parameters of the ARMA(p,q) model (model fitting)



Model fitting = find AR, MA coefficients, and number of such coefficients!

$$X_t = c + \epsilon_t + \sum_{i=1}^{(p)} (\alpha_i) X_{t-i} + \sum_{i=1}^{(q)} (\beta_i) \epsilon_{t-i}$$

# 1) Fitting the ARMA model

## Learning the parameters of the ARMA(p,q) model (model fitting)

### 1) Estimate the number of coefficients p and q

Use an information criterion to select a model (e.g. Akaike IC and Bayesian IC).

### 2) Maximum Likelihood Estimation

Estimating the covariance and mean parameters as a function of the AR and MA parameters.

# 1) Fitting the ARMA model

## Learning the parameters of the ARMA(p,q) model (model fitting)

### 1) Estimate the number of coefficients $p$ and $q$ : use AIC

- Measures relative quality of statistical models for a given set of data.
- Relative estimate of the information lost when a given model is used to represent the process that generates the data.
- Trade-off between the goodness-of-fit of the model and the complexity of that model.

# 1) Fitting the ARMA model

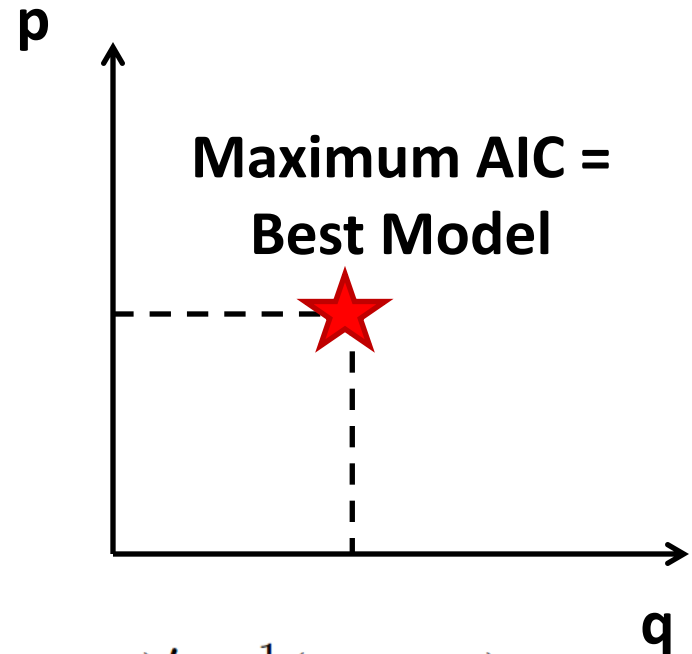
## Learning the parameters of the ARMA(p,q) model (model fitting)

Estimate the number of coefficients p and q: use AIC

$$\text{AIC} = 2pq - 2\log(\ell(p, q))$$

MLE for specific p and q

$$-2\ell(\mu, \phi, \theta, \sigma^2) = n \log 2\pi + \log |\Gamma_n| + (\mathbf{X} - \mu)' \Gamma_n^{-1} (\mathbf{X} - \mu)$$



# 1) ARMA model: pros and cons

## Advantages

Stationarity assumption (coefficients are constant over time) leads to statistical efficiency and ease of construction

## Limitations

Cannot capture complicated or non-stationary dynamics unless upgraded in a way that sacrifices statistical efficiency

**ARMA is usually used in quantitative finance, econometrics, weather forecasting, etc, in order to predict future values of a series**



# 1) ARMA model: key papers

- [1] Harrison, L., William D. Penny, and Karl Friston. "Multivariate autoregressive modeling of fMRI time series." *NeuroImage* 19.4 (2003): 1477-1491.
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## 2) Diffusion models

### Assumptions

Underlying process is:

- Continuous time
- Solves a stochastic differential equation (SDE)
- Has a drift component and a diffusion component
- Usually a Markovian process

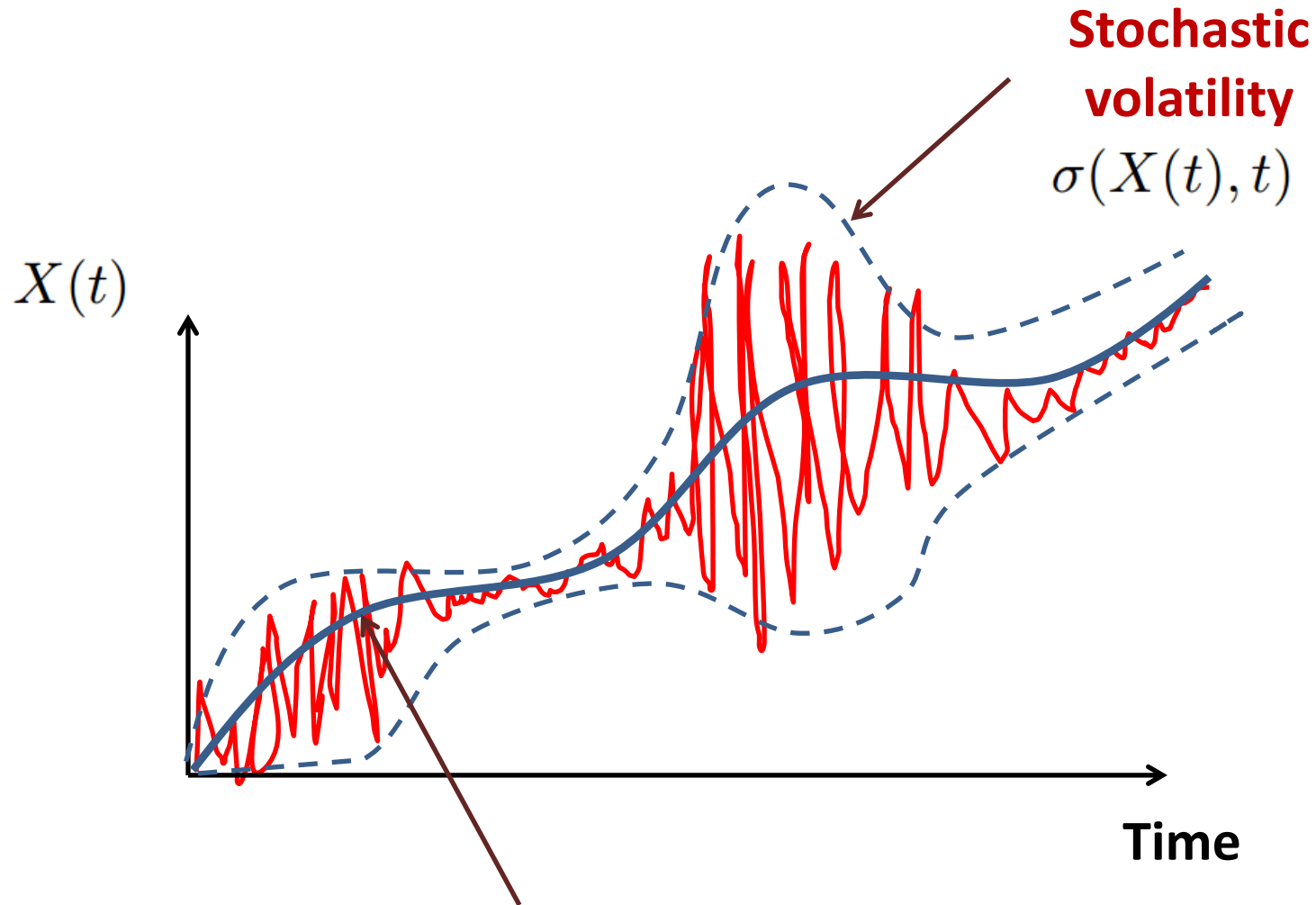
$$dX(t) = \mu(X(t), t) dt + \sigma(X(t), t) dB(t)$$

**Drift component**

**Diffusion  
component**

**Wiener process  
(standard  
Brownian motion)**

## 2) Diffusion models: depiction



$\mu(X(t), t)$  **Drift component (e.g. clinical deterioration)**

## 2) Diffusion models

### Advantages

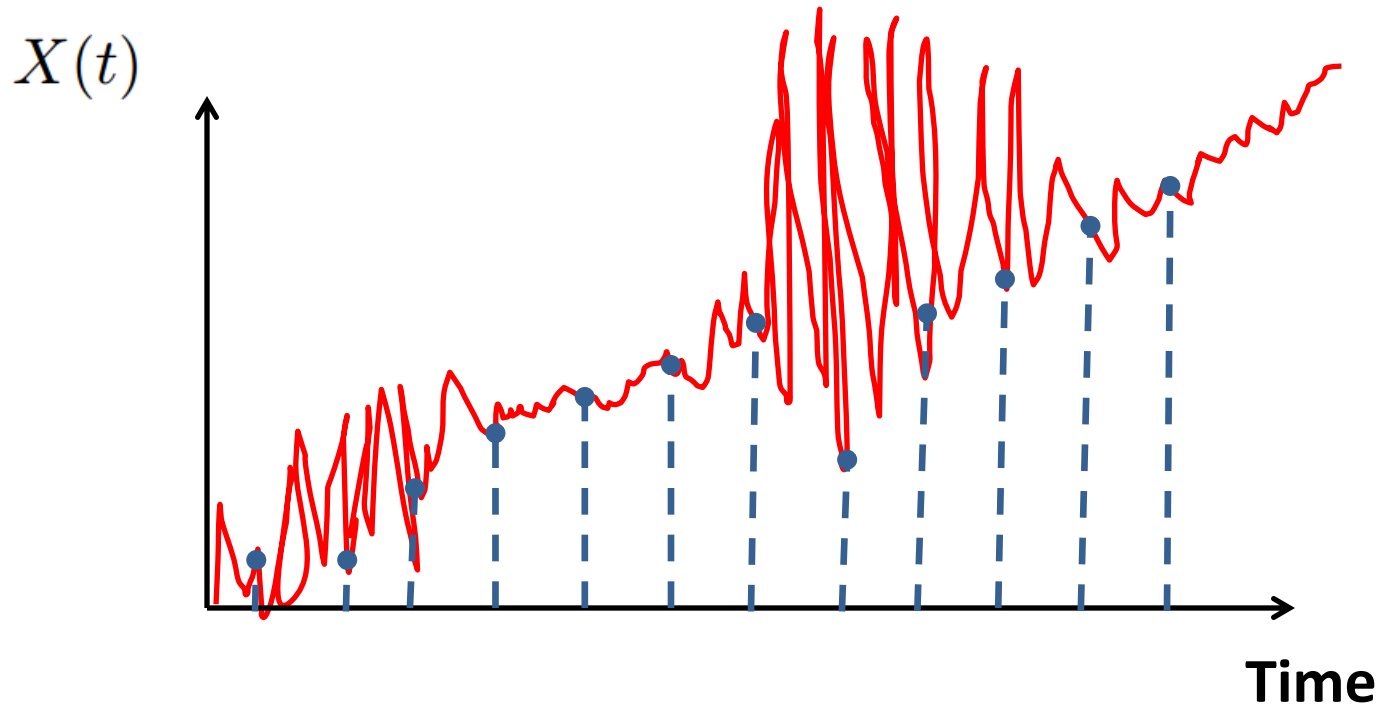
- Models continuous time, some classical results are tractable
- Statistically efficient and non-stationary: only need MLE for **drift** and **stochastic volatility**

### Disadvantages

- In many cases discrete time models suffice especially if sampler is exogenous. Many SDE problems are tedious and intractable.
- Mostly limited to Markovian processes.
- Hard to model relational structure.

Unexplored by ML community, intensively used in quantitative finance

## 2) Diffusion models: depiction



**Brownian motion is the limit of many ARIMA models!**

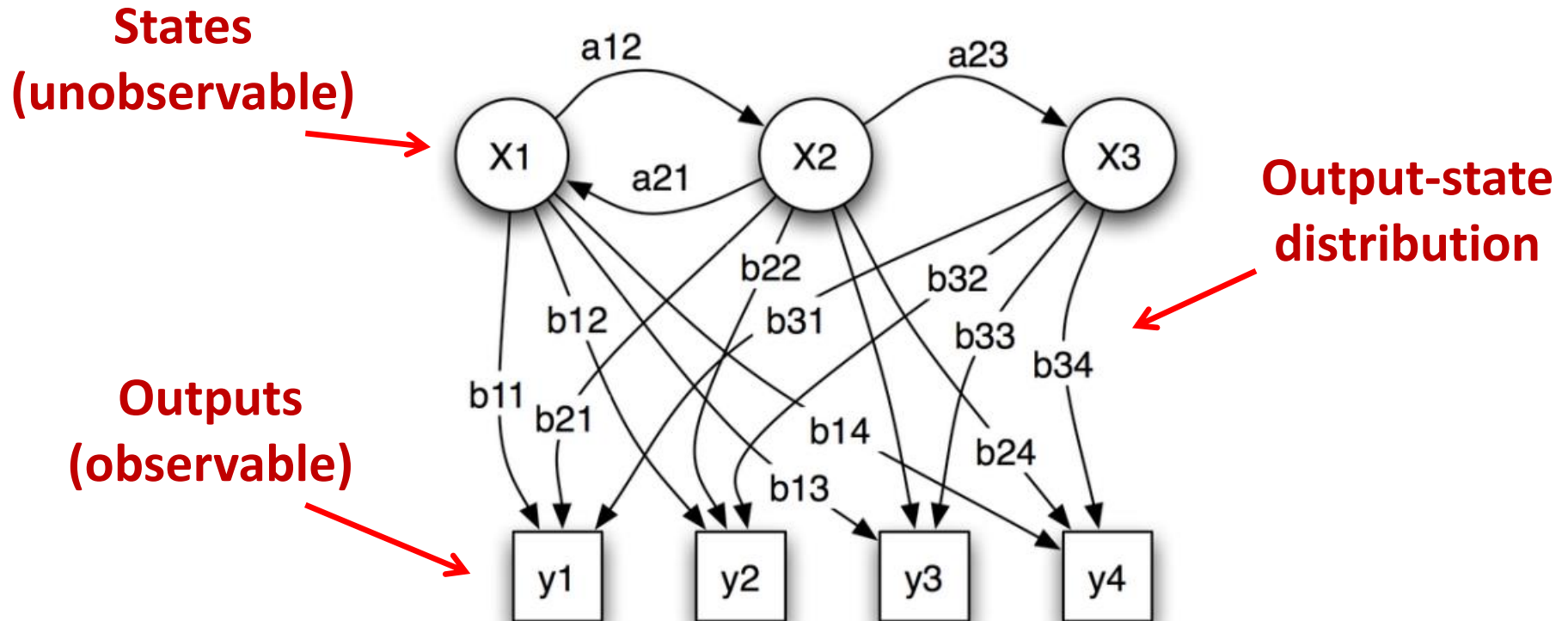
## 2) Diffusion models: key papers

- [1] Holmes, Philip. "Optimal temporal risk assessment." (2011).
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# 3) Hidden Markov Models (HMMs)

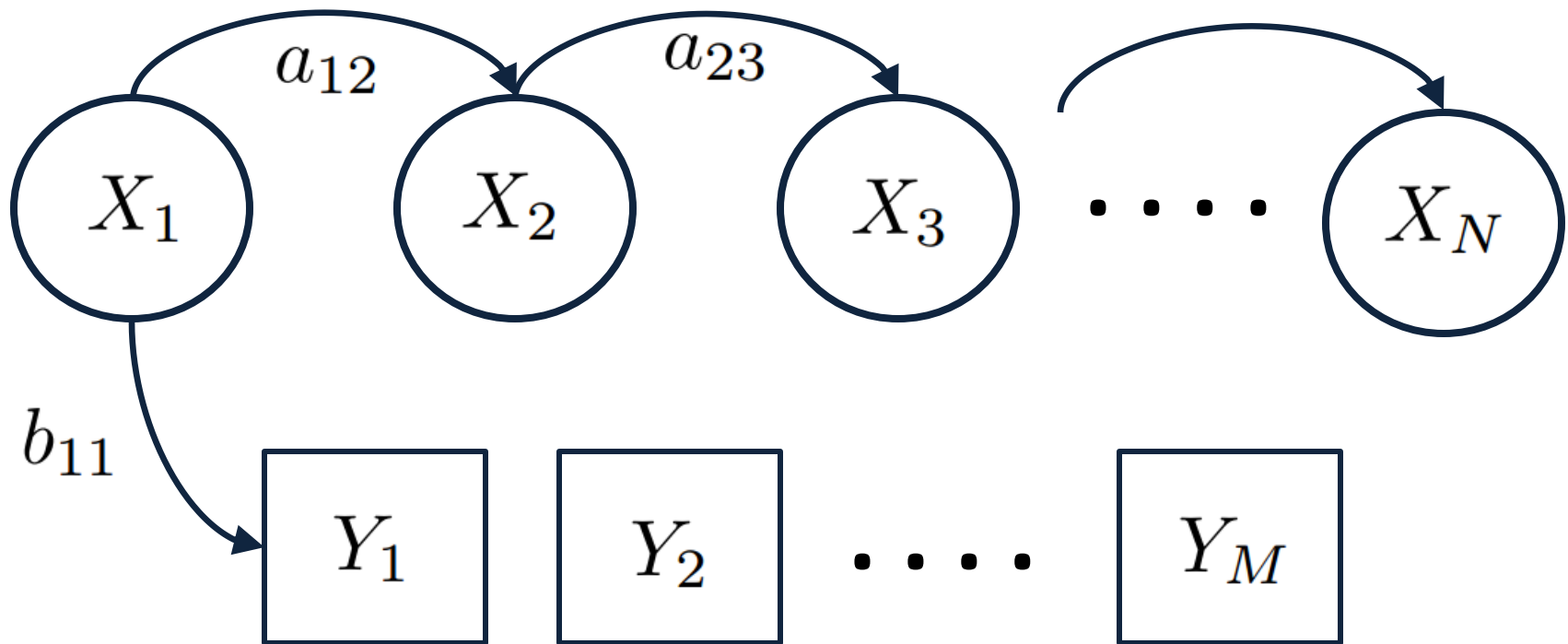
## Assumptions

States are not observable, and what is observed is a set of outputs that are observed with a different probability given each state.



### 3) HMM simulation

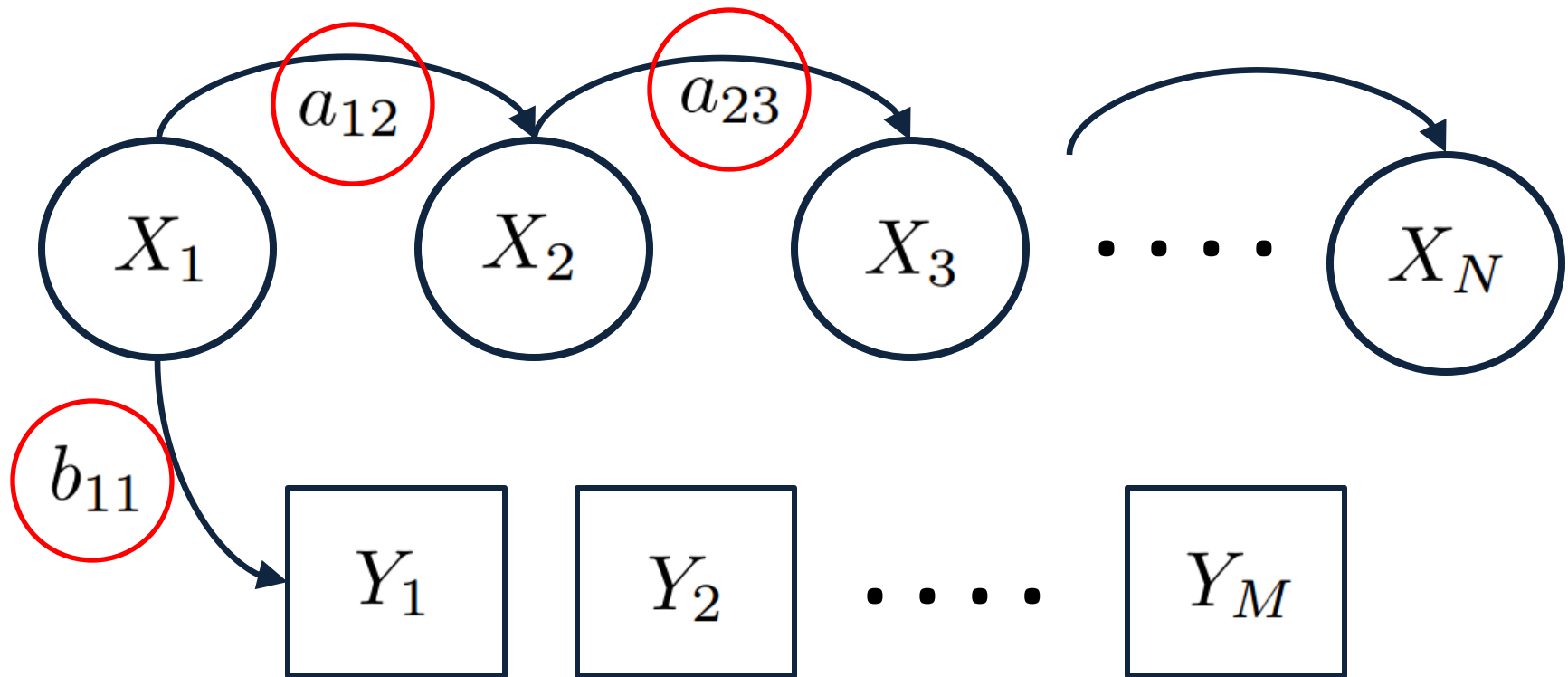
- Observation is a probabilistic function of the state
- HMM is a **doubly embedded stochastic process**





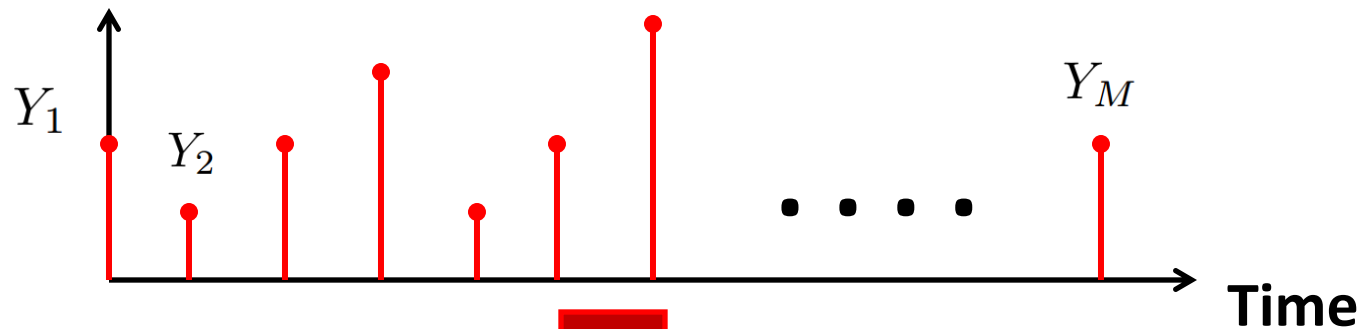
### 3) HMM learning

- Learning an HMM is equivalent to learning the **state-transition probabilities** ( $a_{ij}$ ) and the **emission probabilities** ( $b_{ik}$ )

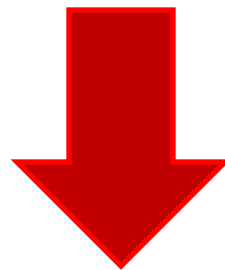


### 3) HMM learning

- Learning an HMM is equivalent to learning the **state-transition probabilities** ( $a_{ij}$ ) and the **emission probabilities** ( $b_{ik}$ ) given an output sequence.



Maximum Likelihood  
Estimation for  $a, b$



$$\arg \max_{a, b} \mathbb{P} (Y_1, Y_2, Y_3, \dots, Y_M | \{a_{ij}\}, \{b_{ij}\})$$

### 3) HMM learning using dynamic programming

#### Algorithms for learning HMMs

1- Brute force: enumerate all output sequences and compute their likelihood -> exponential complexity!

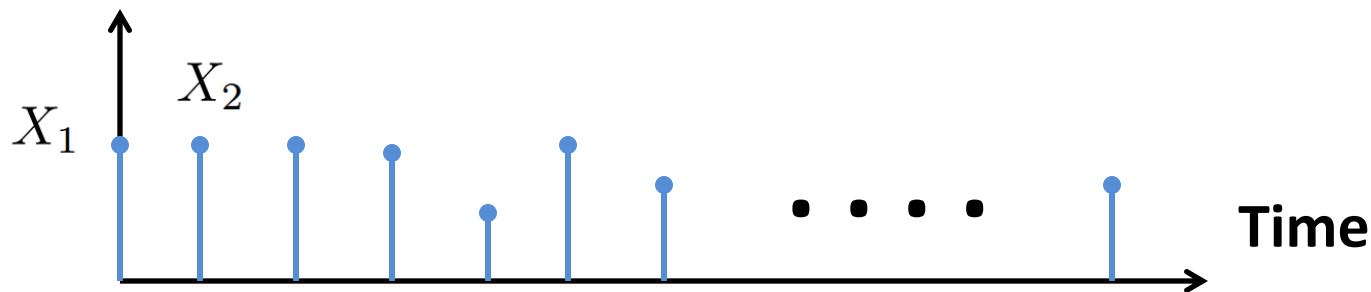
2- Viterbi algorithm (dynamic programming): same idea as Viterbi decoders in convolutional codes.

Used if there is a known state-space that is not observed, and that has a non-injective map to an observed output sequence.

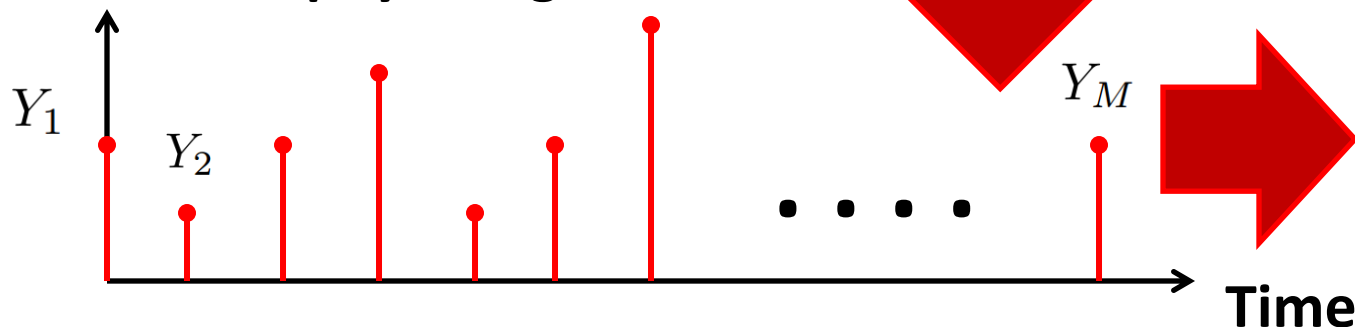
### 3) HMM learning using dynamic programming

HMMs in a medical context (e.g. Martin's problem)

Unobserved true clinical status

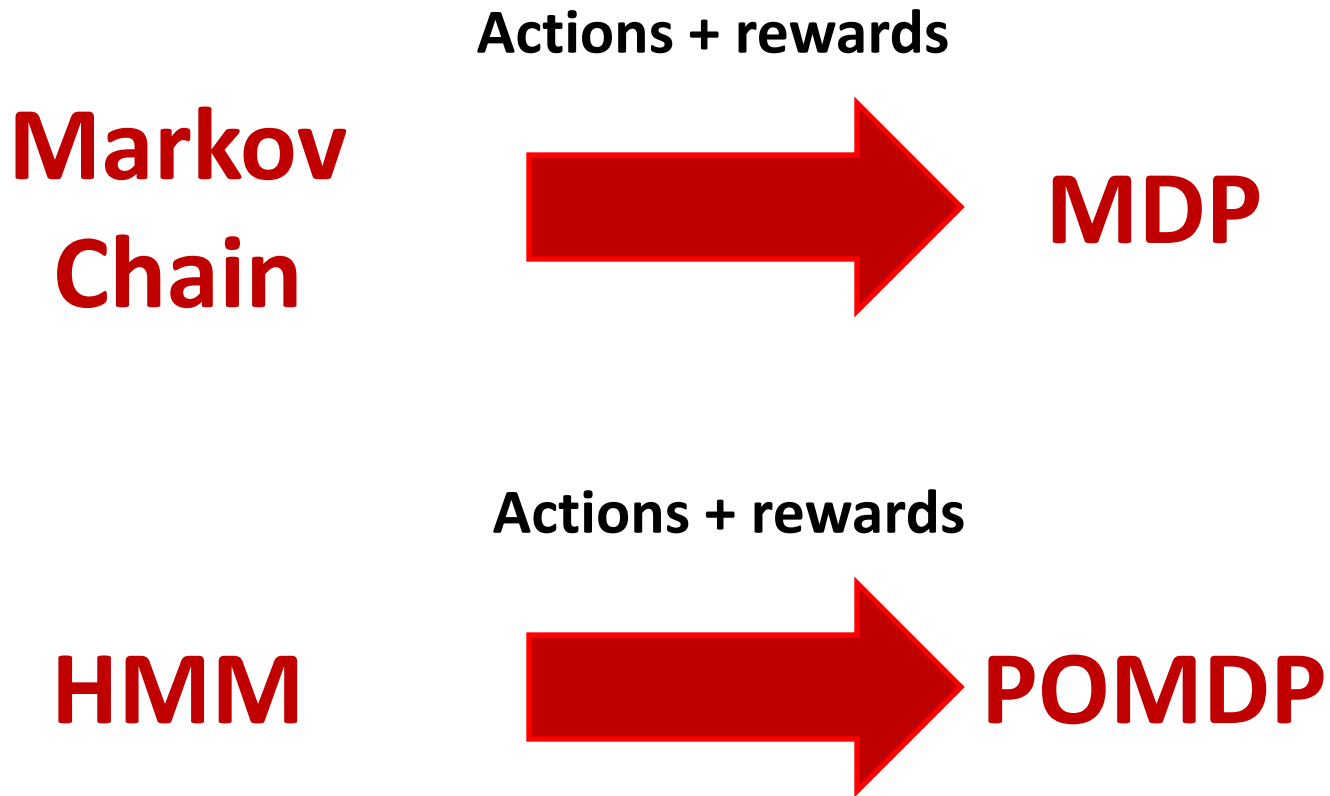


Observed physiological stream



Learn model by  
Viterbi,  
Decoder emits a  
risk score!

### 3) HMM control



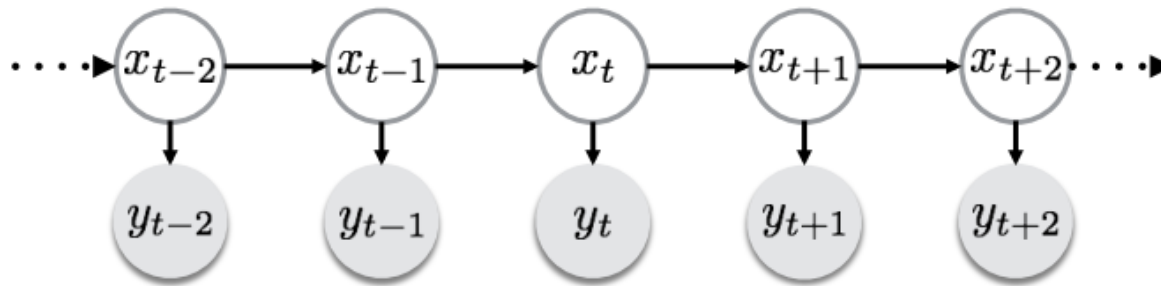
### 3) HMMs: key papers

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- [9] Listgarten, Jennifer, et al. "Multiple alignment of continuous time series." *Advances in neural information processing systems*. 2004.

## 4) State-space model

### Assumptions

- Continuous state-space
- This leads to linearity assumptions for mapping state transitions and states to outputs.

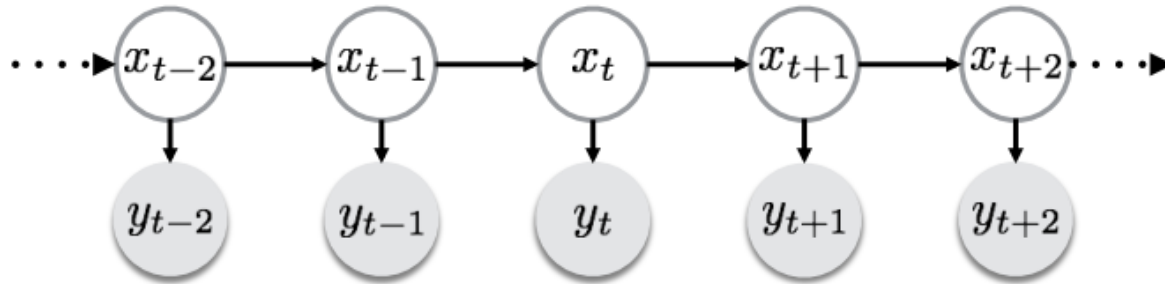


$$x_t = Ax_{t-1} + e_t \quad e_t \sim N(0, \Sigma)$$

$$y_t = Cx_t + w_t \quad w_t \sim N(0, R)$$

## 4) State-space model

**Learning task: finding the matrices mapping states to outputs, and transition matrices across states + covariance of Gaussian noise**

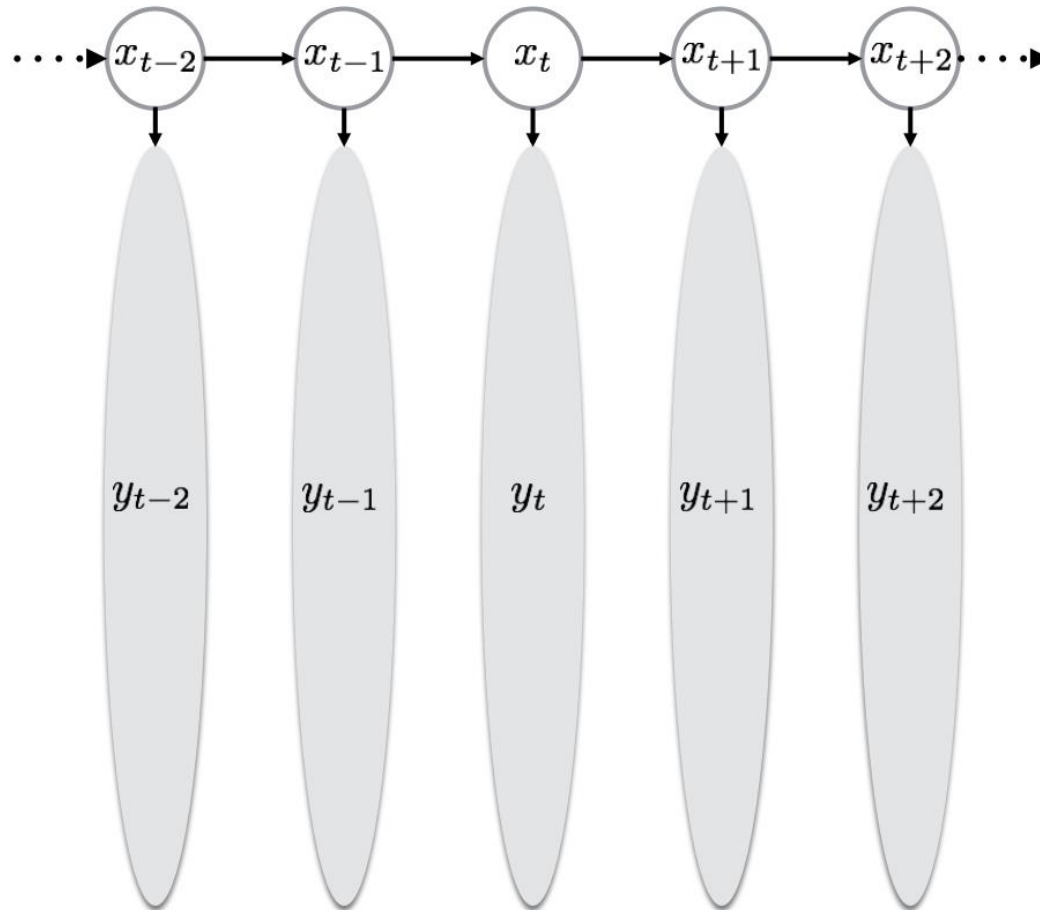


$$x_t = Ax_{t-1} + e_t \quad e_t \sim N(0, \Sigma)$$
$$y_t = Cx_t + w_t \quad w_t \sim N(0, R)$$



## 4) State-space model

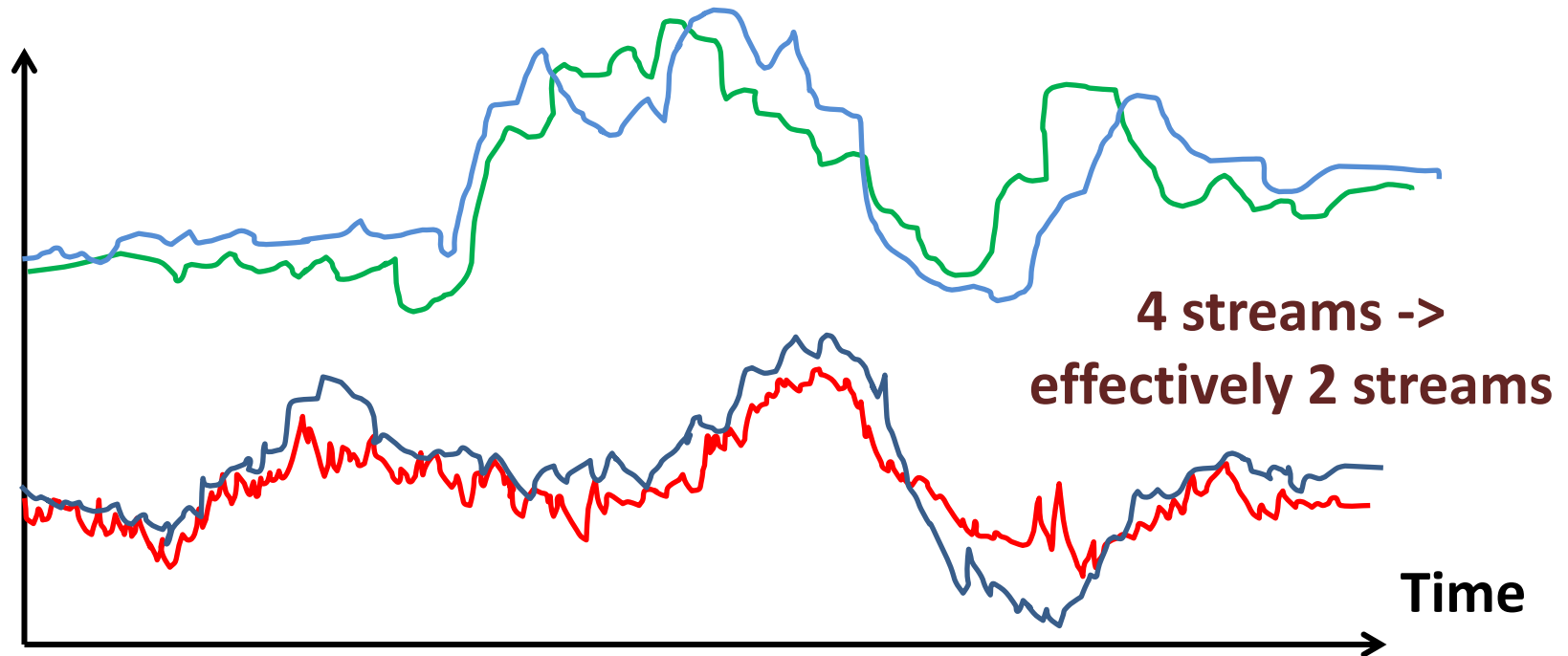
### High-dimensional time series: Large matrices A and C



## 4) State-space model

Some temporal streams are redundant:

How to reduce the dimensionality and capture dynamics?  
Redundancy can be time-varying!!

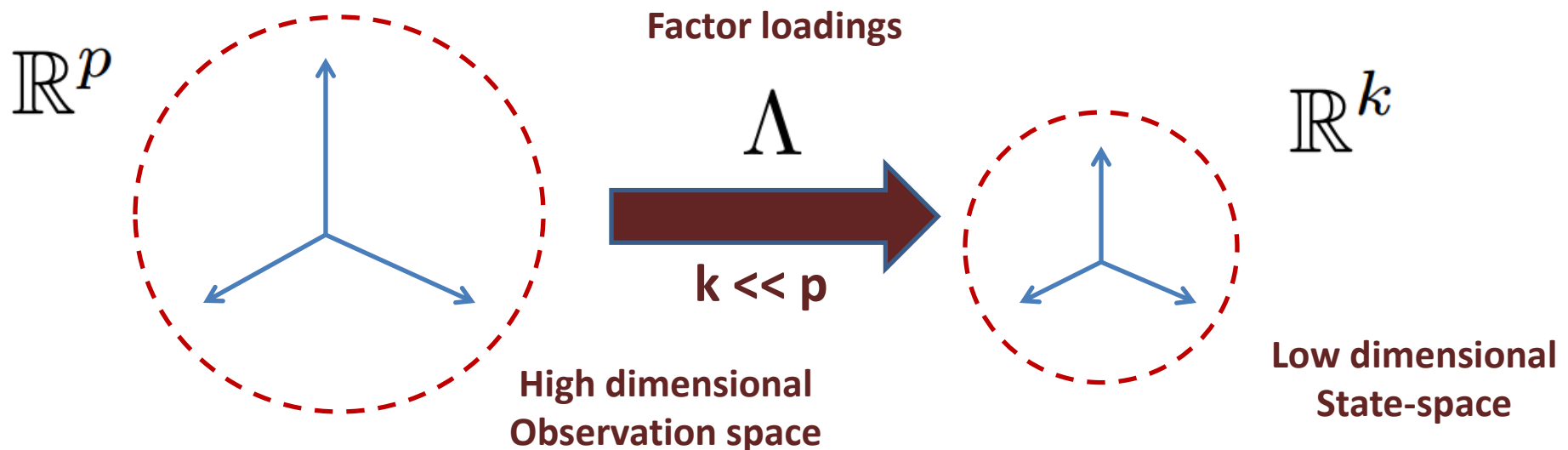


## 5) Dynamic Latent Factor Models

**Goal:** Embed high dimensional time series into a lower dimensional space and maintain the dynamics

**Dynamic functional connectivity (neuroscience) -> Time varying correlations**

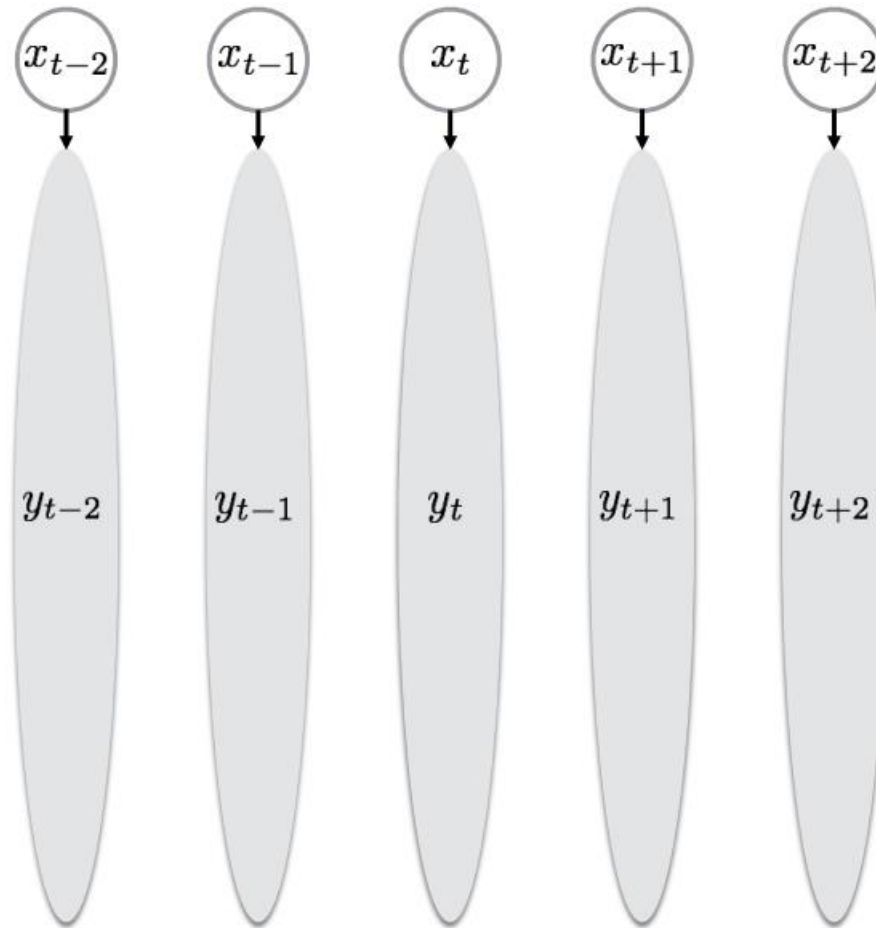
**Models that seek low dimensional embedding of dynamics**



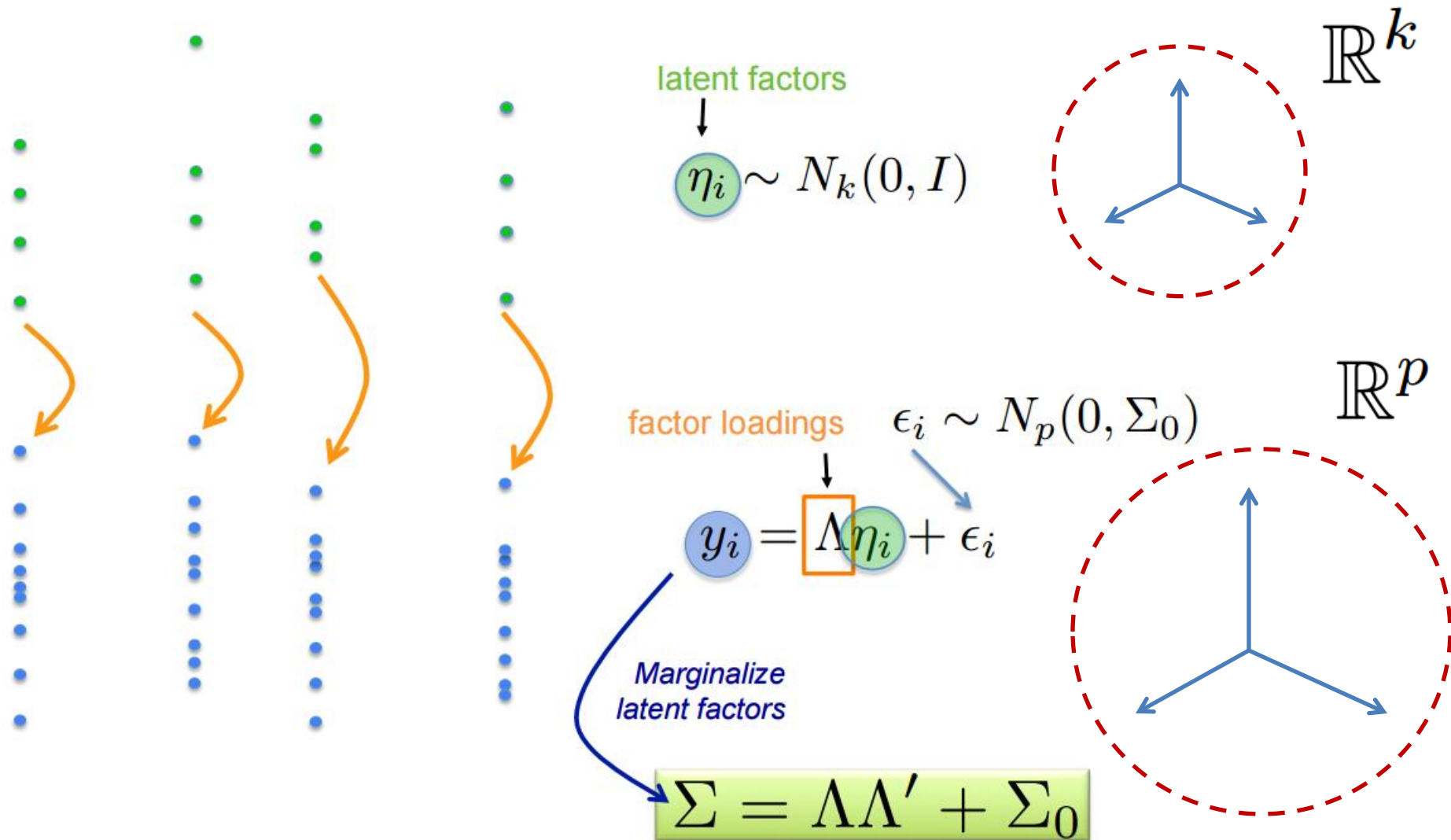
## 5) Dynamic Latent Factor Models

**i.i.d Sequence  
with no  
dynamics =>**

**Latent factor  
model**

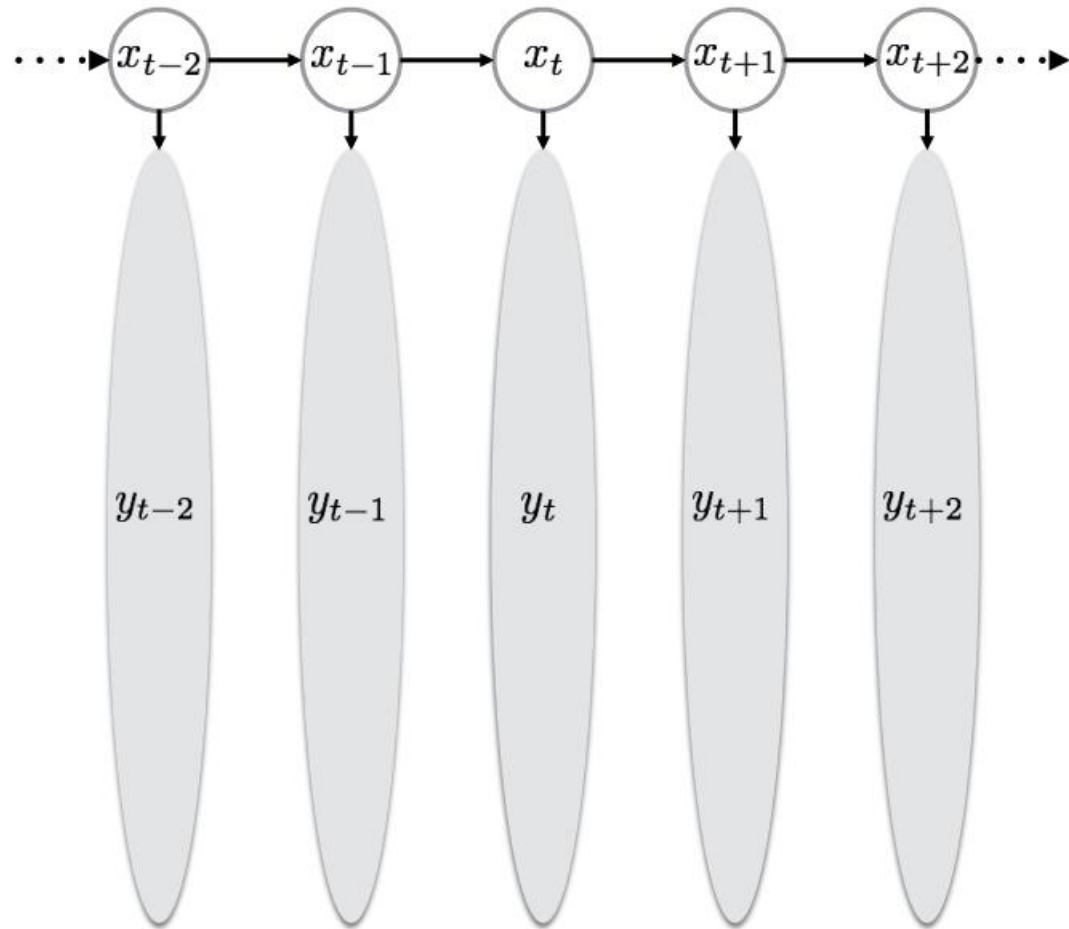


# 5) Dynamic Latent Factor Models



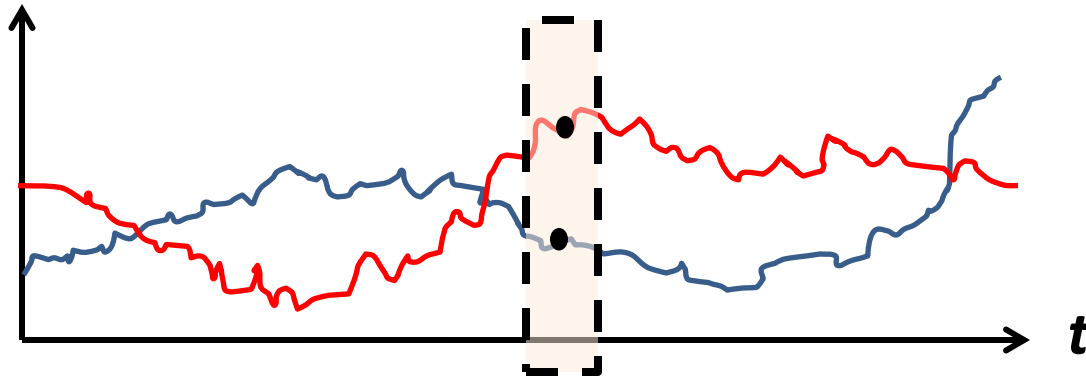
## 5) Dynamic Latent Factor Models

Incorporating  
dynamics =>  
**Dynamic latent  
factor model**



# 5) Dynamic Latent Factor Models

## 2-dimensional state-space dynamics

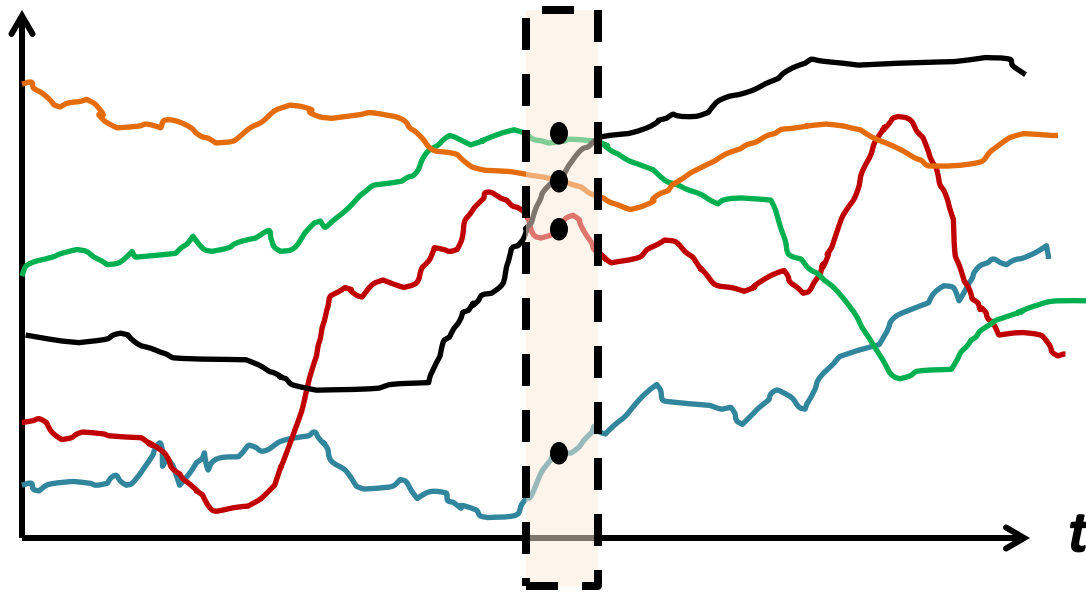


$$\eta_t = \Phi \eta_{t-1} + \nu_t$$

$\nu_t \sim N_k(0, I)$

Evolution of latent factors

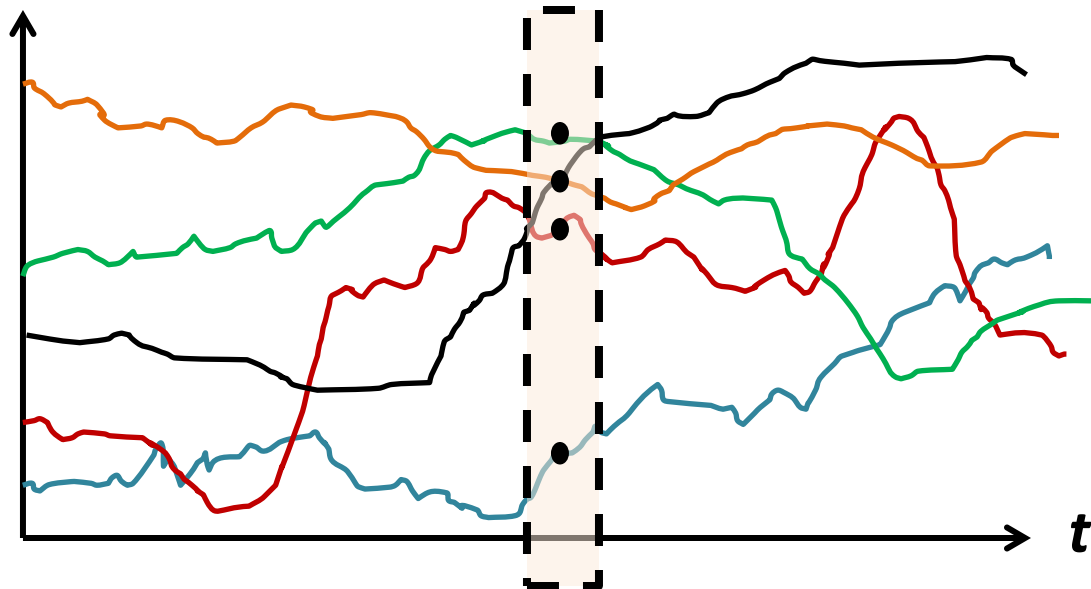
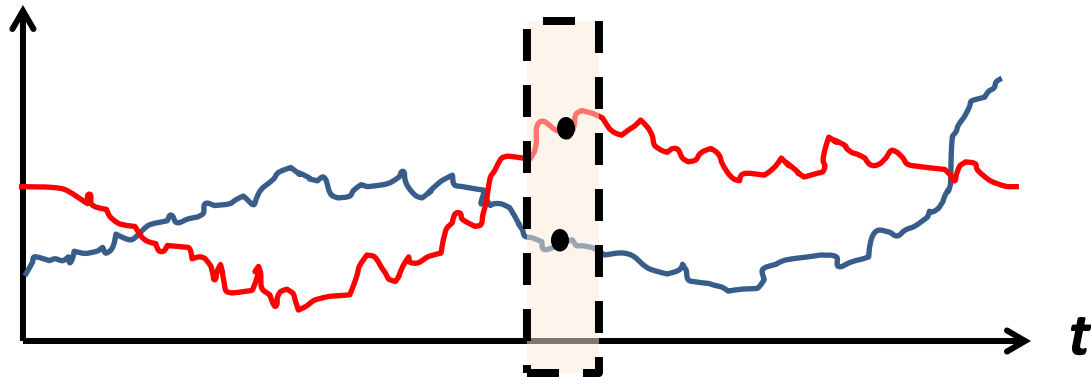
## 5-dimensional observation-space dynamics



$$y_t = \Lambda \eta_t + \epsilon_t$$

$\epsilon_t \sim N_p(0, \Sigma_0)$

## 5) Dynamic Latent Factor Models



**Correlation pattern is still  
Fixed over time!**

$$y_t \sim N(0, \Sigma)$$

$$\Sigma = \Lambda \Sigma_{\eta} \Lambda' + \Sigma_0$$

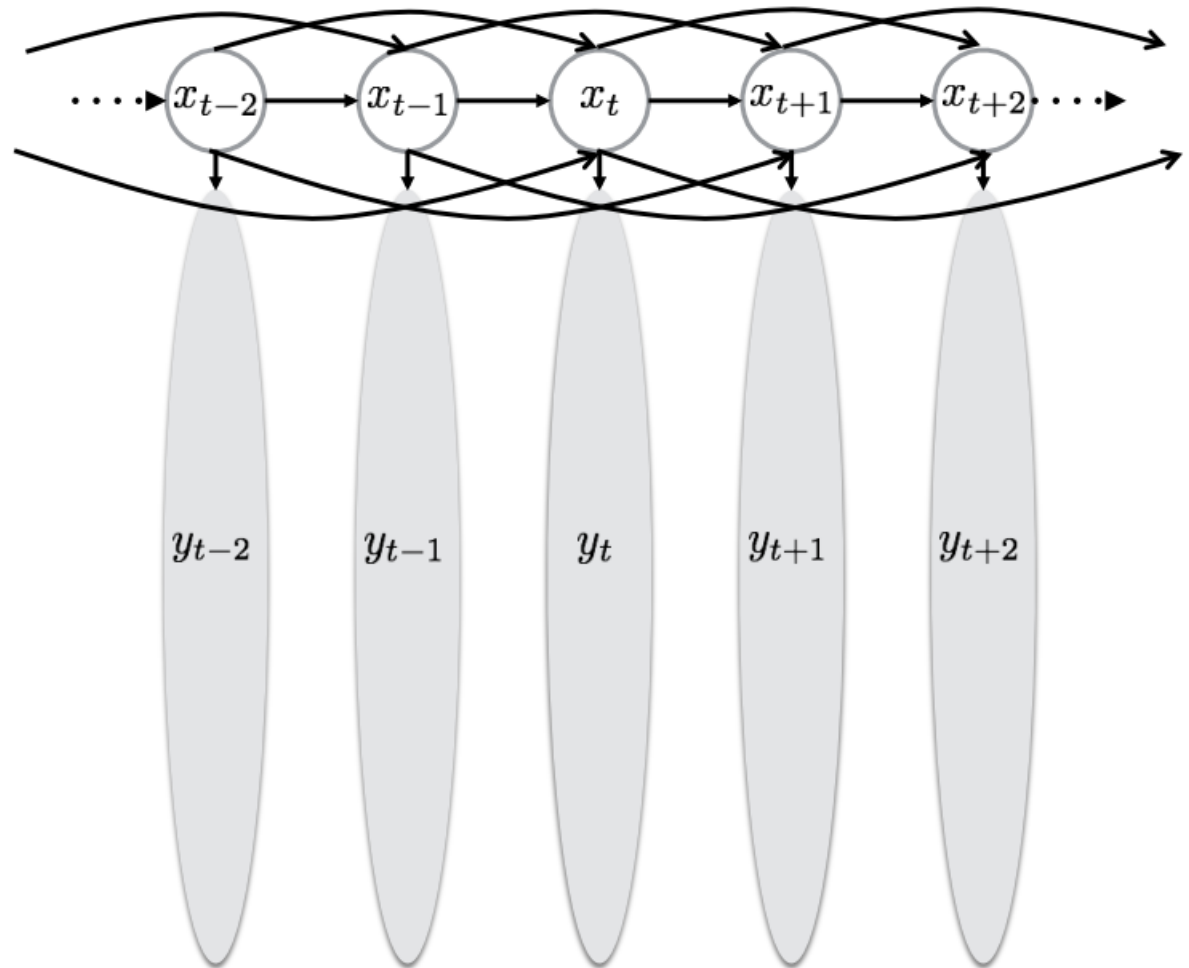
$\Gamma_{\eta}(0)$

**Lag covariance = WSS**

$$\begin{aligned} \Gamma_y(h) &= \text{cov}(y_t, y_{t+h}) \\ &= \Lambda \Gamma_{\eta}(h) \Lambda' \quad h > 0 \end{aligned}$$



## 5) Dynamic Latent Factor Models



Complex  
dynamics=>

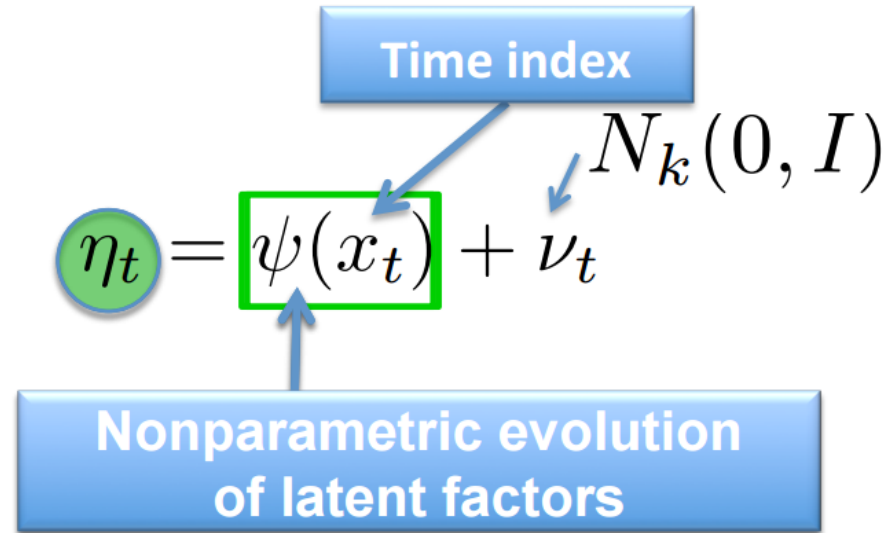
Nonparametric  
latent factor  
evolution

# 5) Dynamic Latent Factor Models

Complex dynamics=>

Nonparametric latent factor evolution

Usually a Gaussian process is used for nonparametric evolution



$$y_t = \Lambda \eta_t + \epsilon_t$$

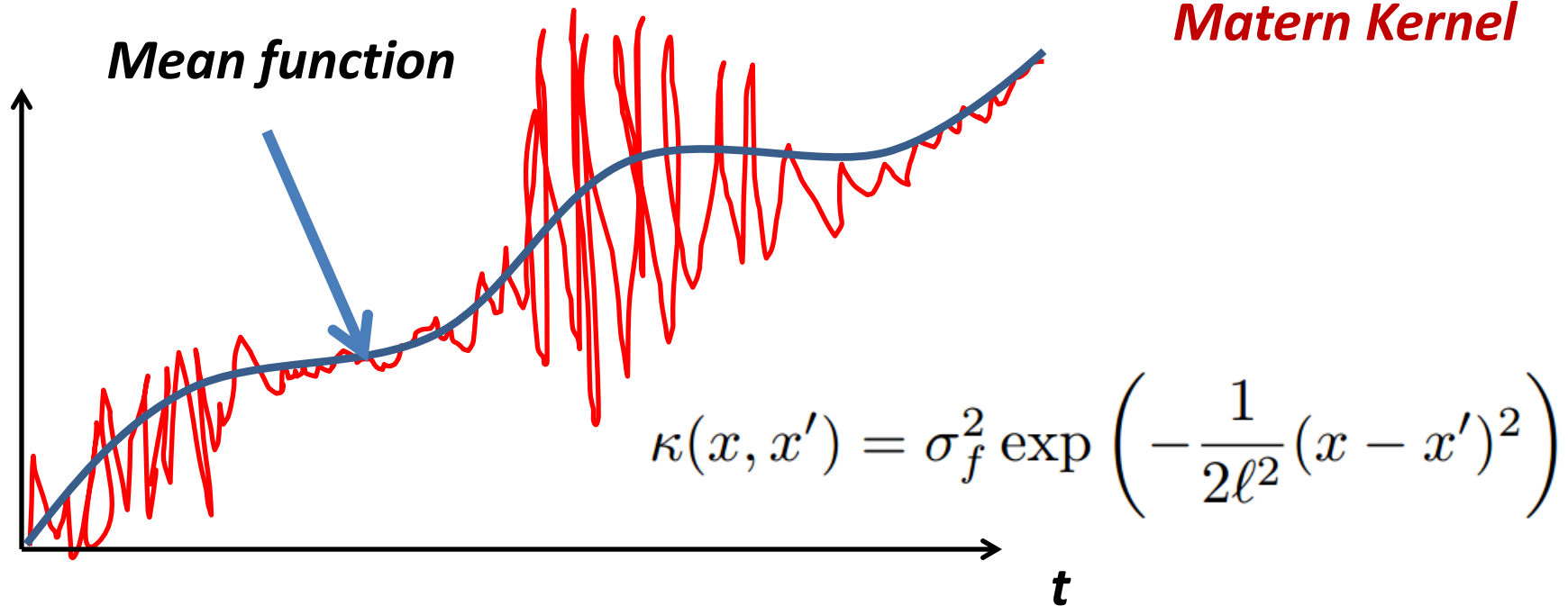
A blue arrow points from the text  $N_p(0, \Sigma_0)$  to the noise term  $\epsilon_t$ .

## 5) Dynamic Latent Factor Models

# What is a Gaussian Process?

- Distribution over functions  $f \sim \text{GP}(m, K)$
- $m$ : mean function,  $K$ : covariance Kernel

*Brownian motion  
is a GP with  
Matern Kernel*

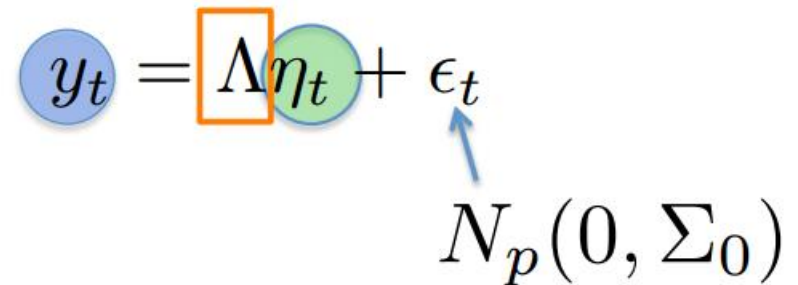
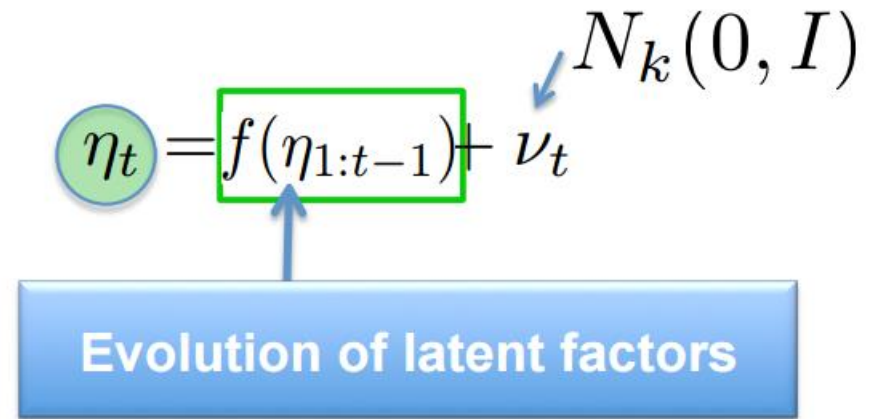


## 5) Dynamic Latent Factor Models

Fit the latent factor process using GP regression

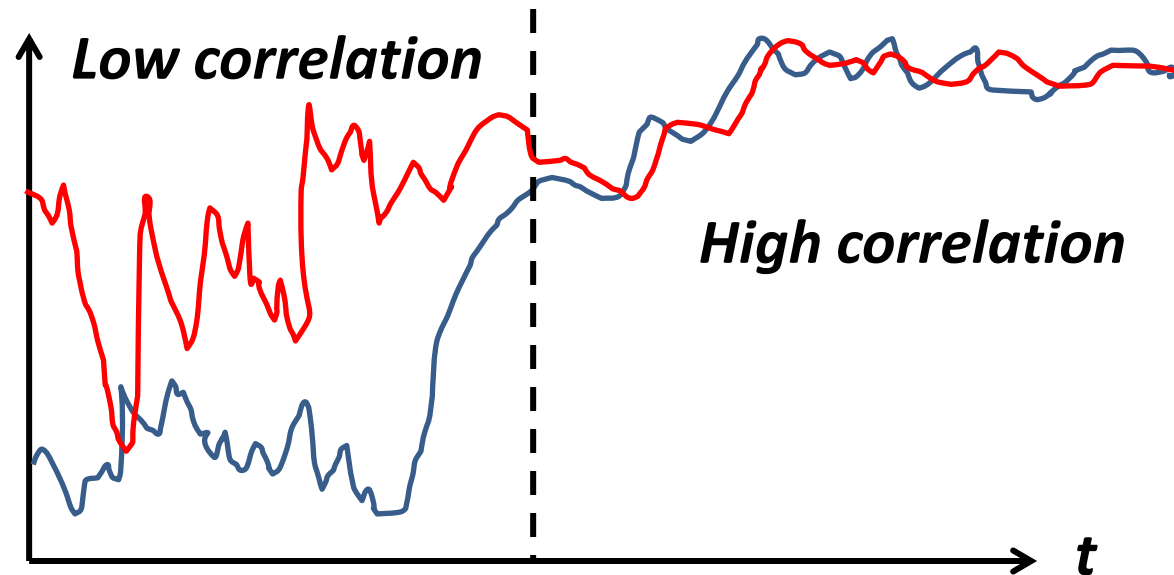
=>

Get  $f(\cdot)$



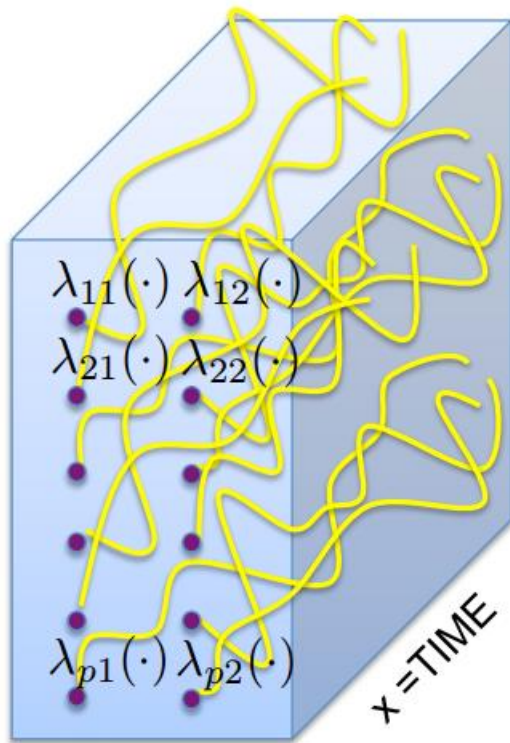
## 5) Dynamic Latent Factor Models

We modeled **EVOLUTION** by a GP, but  
How to capture the changing  
correlation pattern  
(**RELATIONAL STRUCTURE**)?



## 5) Dynamic Latent Factor Models

Model every entry in Latent factor matrix by a GP



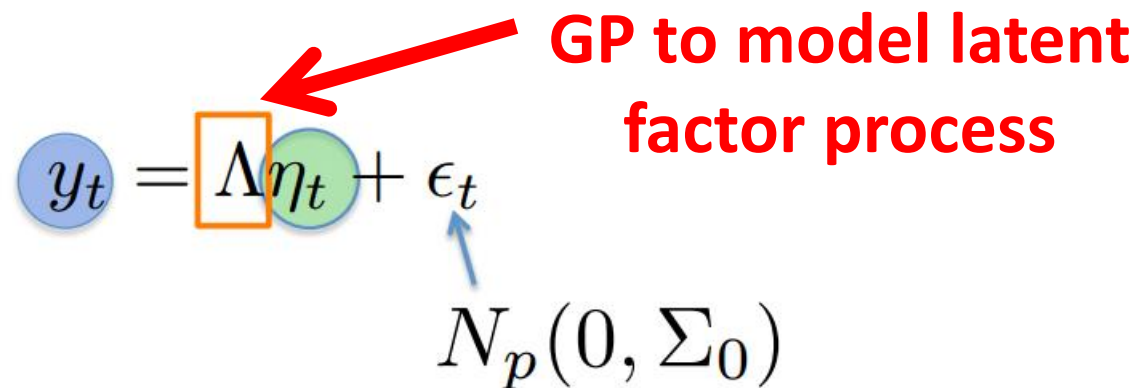
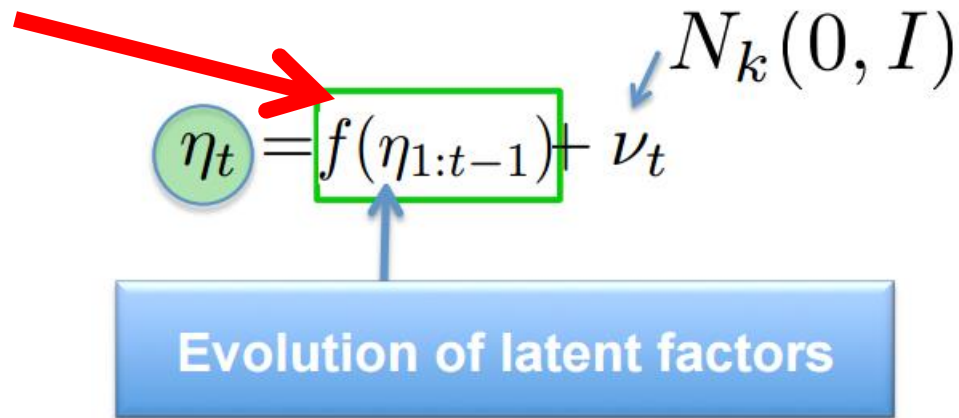
$p \times k$  array of  
processes over time

$$k \ll p$$

$$\Sigma(x) = \Lambda(x) \Lambda(x)' + \Sigma_0$$

# 5) Dynamic Latent Factor Models

**GP to model evolution  
and dynamics**



## 5) Dynamic Latent Factor Models

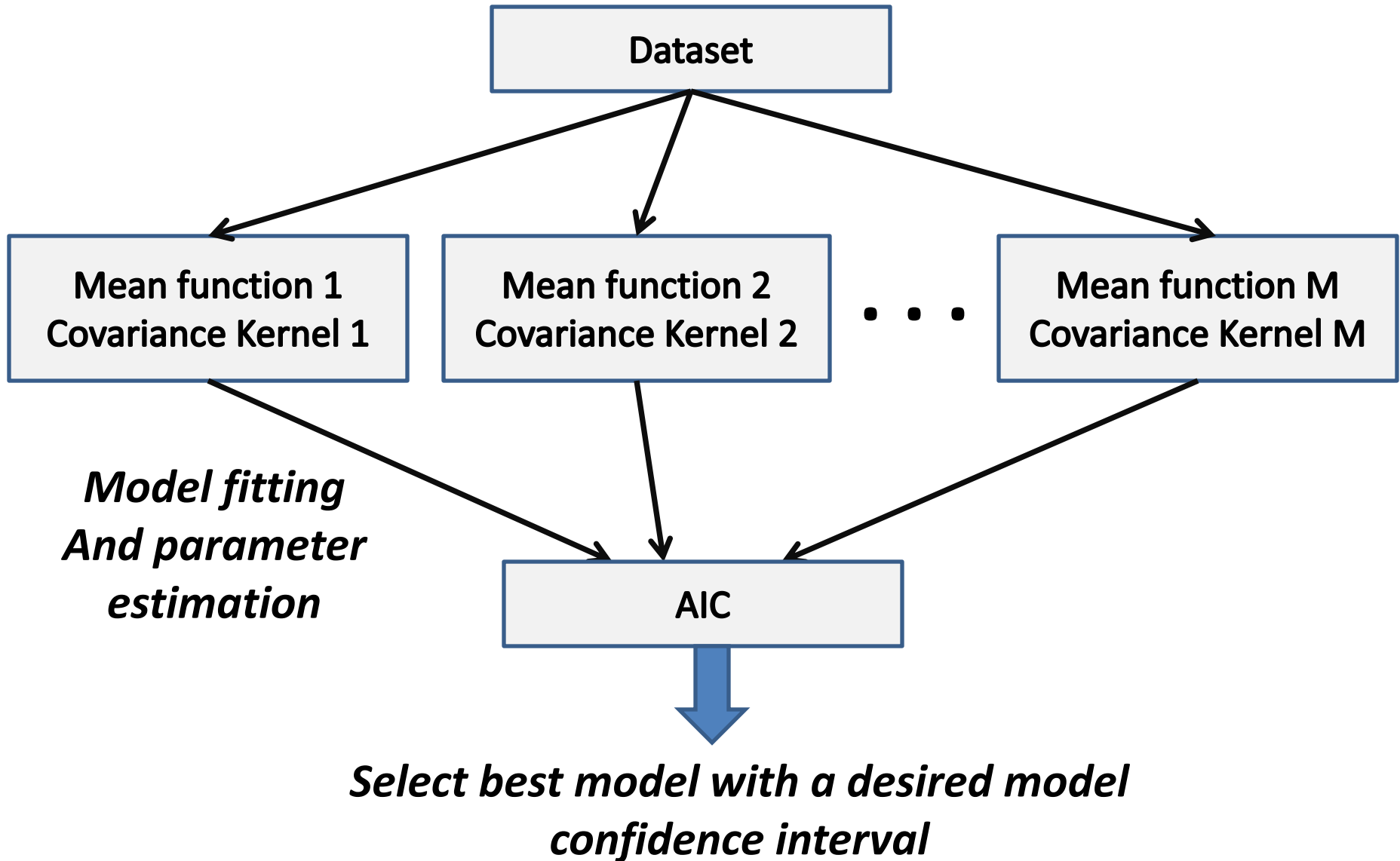
**Conclusion:** Dynamic Latent Factor Model can capture complicated dynamics and encapsulates most of other models



## 5) Dynamic Latent Factor Model: key papers

- [1] Zhang, Yongyue, Michael Brady, and Stephen Smith. "Segmentation of brain MR images through a hidden Markov random field model and the expectation-maximization algorithm." *Medical Imaging, IEEE Transactions on* 20.1 (2001): 45-57.
- [2] Andreão, Rodrigo Varejão, Bernadette Dorizzi, and Jérôme Boudy. "ECG signal analysis through hidden Markov models." *Biomedical Engineering, IEEE Transactions on* 53.8 (2006): 1541-1549.
- [3] Coast, Douglas A., et al. "An approach to cardiac arrhythmia analysis using hidden Markov models." *Biomedical Engineering, IEEE Transactions on* 37.9 (1990): 826-836.
- [4] Oates, Tim, Laura Firoiu, and Paul R. Cohen. "Using dynamic time warping to bootstrap HMM-based clustering of time series." *Sequence Learning*. Springer Berlin Heidelberg, 2000. 35-52.
- [5] Oates, Tim, Laura Firoiu, and Paul R. Cohen. "Clustering time series with hidden markov models and dynamic time warping." *Proceedings of the IJCAI-99 workshop on neural, symbolic and reinforcement learning methods for sequence learning*. Sweden Stockholm, 1999.
- [6] Oates, Tim, Laura Firoiu, and Paul R. Cohen. "Clustering time series with hidden markov models and dynamic time warping." *Proceedings of the IJCAI-99 workshop on neural, symbolic and reinforcement learning methods for sequence learning*. Sweden Stockholm, 1999.
- [7] Pavlovic, Vladimir, Brendan J. Frey, and Thomas S. Huang. "Time-series classification using mixed-state dynamic Bayesian networks." *Computer Vision and Pattern Recognition, 1999. IEEE Computer Society Conference on.. Vol. 2*. IEEE, 1999.
- [8] Li, Sheng-Tun, and Yi-Chung Cheng. "A stochastic HMM-based forecasting model for fuzzy time series." *Systems, Man, and Cybernetics, Part B: Cybernetics, IEEE Transactions on* 40.5 (2010): 1255-1266.
- [9] Listgarten, Jennifer, et al. "Multiple alignment of continuous time series." *Advances in neural information processing systems*. 2004.

# Model Selection



## Further topics to discuss.....

- **Dynamic Bayesian networks:** modeling cause and effect
- **Real-time Cox regression:** survival analysis based on time series
- **Structure learning:** learning graphs of patients, treatments, etc, based on time series
- **Time series clustering:** personalization!